

On Space-Time Singularities, Holes, and Extensions

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Here, we clarify the relationship among three space-time conditions of interest: geodesic completeness, hole-freeness, and inextendibility. In addition, we introduce a related fourth condition: effective completeness.

1. Introduction. In what follows, we consider three space-time conditions of interest: geodesic completeness, hole-freeness, and inextendibility. How are these three conditions related? Here, we review what is known and contribute a few (minor) results of our own. We take no position as to which of these conditions are satisfied by any or all physically reasonable space-times.¹ We seek only to shed light on the connections among them.

2. Background Structure. We begin with a few preliminaries concerning the relevant background formalism of general relativity.² An n -dimensional, relativistic *space-time* (for $n \geq 2$) is a pair of mathematical objects (M, g_{ab}) . Object M is a connected n -dimensional manifold (without boundary) that is smooth (infinitely differentiable). Here, g_{ab} is a smooth, nondegenerate, pseudo-Riemannian metric of Lorentz signature $(+, -, \dots, -)$ defined on M .

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1. In the literature, geodesic completeness is usually taken to be violated by some physically reasonable space-times, while hole-freeness and inextendibility are usually taken to be satisfied by all such space-times. See, e.g., Clarke (1976, 1993) and Earman (1989, 1995).

2. The reader is encouraged to consult Hawking and Ellis (1973) and Wald (1984) for details. An outstanding (and less technical) survey of the global structure of space-time is given by Geroch and Horowitz (1979).

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Note that M is assumed to be *Hausdorff*; for any distinct $p, q \in M$, one can find disjoint open sets O_p and O_q containing p and q , respectively. We say two space-times (M, g_{ab}) and (M', g'_{ab}) are *isometric* if there is a diffeomorphism $\varphi : M \rightarrow M'$ such that $\varphi_*(g_{ab}) = g'_{ab}$.

For each point $p \in M$, the metric assigns a cone structure to the tangent space M_p . Any tangent vector ξ^a in M_p will be *timelike* if $g_{ab}\xi^a\xi^b > 0$, *null* if $g_{ab}\xi^a\xi^b = 0$, or *spacelike* if $g_{ab}\xi^a\xi^b < 0$. Null vectors create the cone structure; timelike vectors are inside the cone, while spacelike vectors are outside. A *time orientable* space-time is one that has a continuous timelike vector field on M . A time orientable space-time allows one to distinguish between future and past lobes of the light cone. In what follows, it is assumed that space-times are time orientable.

For some open (connected) interval $I \subseteq \mathbb{R}$, a smooth curve $\gamma : I \rightarrow M$ is *timelike* if the tangent vector ξ^a at each point in $\gamma[I]$ is timelike. Similarly, a curve is *null* (respectively, *spacelike*) if its tangent vector at each point is null (respectively, spacelike). A curve is *causal* if its tangent vector at each point is either null or timelike. A causal curve is *future directed* if its tangent vector at each point falls in or on the future lobe of the light cone.

We say a curve $\gamma : I \rightarrow M$ is not *maximal* if there is another curve $\gamma' : I' \rightarrow M$ such that I is a proper subset of I' and $\gamma(s) = \gamma'(s)$ for all $s \in I$. A curve $\gamma : I \rightarrow M$ in a space-time (M, g_{ab}) is a *geodesic* if $\xi^a \nabla_a \xi^b = 0$, where ξ^a is the tangent vector and Δ_a is the unique derivative operator compatible with g_{ab} .

For any two points $p, q \in M$, we write $p \ll q$ if there exists a future-directed timelike curve from p to q . We write $p < q$ if there exists a future-directed causal curve from p to q . These relations allow us to define the timelike and causal pasts and futures of a point p : $I^-(p) = \{q : q \ll p\}$, $I^+(p) = \{q : p \ll q\}$, $J^-(p) = \{q : q < p\}$, and $J^+(p) = \{q : p < q\}$. Naturally, for any set $S \subseteq M$, define $J^+[S]$ to be the set $\cup\{J^+(x) : x \in S\}$, and so on. A set $S \subset M$ is *achronal* if $S \cap I^-[S] = \emptyset$. We say a space-time (M, g_{ab}) is *stably causal* if there is a smooth function $f : M \rightarrow \mathbb{R}$ such that, for any distinct points $p, q \in M$, if $p \in J^+(q)$, then $f(p) > f(q)$.

A point $p \in M$ is a *future endpoint* of a future-directed causal curve $\gamma : I \rightarrow M$ if, for every neighborhood O of p , there exists a point $t_0 \in I$ such that $\gamma(t) \in O$ for all $t > t_0$. A *past endpoint* is defined similarly. A causal curve is *future inextendible* (respectively, *past inextendible*) if it has no future (respectively, past) endpoint.

For any set $S \subseteq M$, we define the *past domain of dependence* of S , written $D^-(S)$, to be the set of points $p \in M$ such that every causal curve with past endpoint p and no future endpoint intersects S . The *future domain of dependence* of S , written $D^+(S)$, is defined analogously. The entire *domain of dependence* of S , written $D(S)$, is just the set $D^-(S) \cup D^+(S)$. The *edge* of an achronal set $S \subset M$ is the collection of points $p \in S$ such that every open

neighborhood O of p contains a point $q \in I^+(p)$, a point $r \in I^-(p)$, and a timelike curve from r to q that does not intersect S . A set $S \subset M$ is a *slice* if it is closed, achronal, and without edge. A space-time (M, g_{ab}) that contains a slice S such that $D(S) = M$ is said to be *globally hyperbolic*.

3. Singularities and Holes. There are a number of ways to define a space-time singularity but “none, with the exception of geodesic incompleteness, seems to have found any significant applications” (Geroch and Horowitz 1979, 258). Here, we take this position for granted and refer the reader to Curiel (1999) for thorough and convincing arguments in its favor. We now make the condition precise.

DEFINITION 1.—A space-time (M, g_{ab}) is *geodesically complete* (GC) if every maximal geodesic $\gamma : I \rightarrow M$ is such that $I = \mathbb{R}$. A space-time is *geodesically incomplete* if it is not geodesically complete.

Physically, a timelike incomplete geodesic represents a freely falling observer who does not record all possible watch readings. If an incomplete geodesic is timelike or null, there is a useful distinction one can introduce. We say that a future-directed timelike or null geodesic $\gamma : I \rightarrow M$ without future endpoint is *future incomplete* if there is an $r \in \mathbb{R}$ such that $s < r$ for all $s \in I$. A *past incomplete* timelike or null geodesic is defined analogously.

The singularity theorems of Hawking and Penrose (1970) show that a large number of seemingly physically reasonable space-times fail to be geodesically complete. Thus, the condition is somewhat strong.

Of course, there are also a large number of geodesically incomplete space-times that seem to have “artificial” singularities. Indeed one can show that any space-time with one point removed from the manifold is geodesically incomplete. In such a space-time, a type of indeterminism is also present; the domain of dependence of some spacelike surface is not “as large as it could have been.” We turn our attention now to this type of indeterminism—due to space-time “holes”—and its connections with geodesic incompleteness.

Initially, one defined (Geroch 1977) a space-time (M, g_{ab}) to be *hole-free* if, for every spacelike surface $S \subset M$ and every isometric embedding $\varphi : D(S) \rightarrow M'$ into some other space-time (M', g'_{ab}) , we have $\varphi(D(S)) = D(\varphi(S))$. The definition seemed to be satisfactory. Indeed, one can show that any space-time with one point removed from the manifold is not hole-free. But surprisingly, it turns out that the definition is too strong; Minkowski space-time fails to be hole-free under this formulation (Krasnikov 2009). But one can make minor modifications to avoid this consequence (Manchak 2009).

Let (K, g_{ab}) be a globally hyperbolic space-time. Let $\varphi : K \rightarrow K'$ be an isometric embedding into a space-time (K', g'_{ab}) . We say (K', g'_{ab}) is an *ef-*

fective extension of (K, g_{ab}) if, for some Cauchy surface S in (K, g_{ab}) , $\varphi[K] \not\subseteq \text{int}(D(\varphi[S]))$ and $\varphi[S]$ is achronal. Hole-freeness can then be defined as follows.

DEFINITION 2.—A space-time (M, g_{ab}) is *hole-free* (HF) if, for every set $K \subseteq M$ such that $(K, g_{ab|K})$ is a globally hyperbolic space-time with Cauchy surface S , if $(K', g_{ab|K'})$ is not an effective extension of $(K, g_{ab|K})$ where $K' = \text{int}(D(S))$, then there is no effective extension of $(K, g_{ab|K})$.

What is the relationship between hole-freeness and geodesic completeness? One can easily show that the former does not imply the latter.

EXAMPLE 1.—Let $(\mathbb{R}^2, \eta_{ab})$ be Minkowski space-time, and let p be any point in \mathbb{R}^2 , and let q be any point in $I^-(p)$. Let M be the manifold $I^-(p) \cap I^+(q)$. Clearly, the space-time $(M, \eta_{ab|M})$ satisfies HF but not GC.

One wonders whether the implication relation holds in the other direction. And it has been conjectured by Geroch (private communication) that there even exists some physically significant intermediate completeness condition that is weaker than geodesic completeness but stronger than hole-freeness (see fig. 1).

Why might such an intermediate condition be of interest? As noted above, geodesic completeness is a somewhat strong condition in the sense that not all seemingly physically reasonable space-times satisfy it. However, hole-freeness is a somewhat weak condition in the sense that some space-times (e.g., example 1) that satisfy it can be constructed by removing points from otherwise geodesically complete space-times. An intermediate condition may be strong enough to rule out these seemingly artificial singularities but weak enough to allow the more physically reasonable, geodesically incomplete space-times guaranteed by the singularity theorems.

4. Singularities and Extensions. One way to rule out space-times that are constructed by removing points from the manifold is to require that space-time be “as large as it could have been.” In other words, one can require that space-time be inextendible. We have the following definition.

DEFINITION 3.—A space-time (M, g_{ab}) is *extendible* if there exists a space-time (M', g'_{ab}) and an isometric embedding $\varphi : M \rightarrow M'$ such that

$$(GC) \implies ? \implies (HF)$$

Figure 1. Is there a physically significant intermediate condition that is implied by GC and implies HF?

$\varphi(M) \subsetneq M'$. Here, the space-time (M', g'_{ab}) is an *extension* of (M, g_{ab}) . A space-time is *inextendible* (I) if it has no extension.

One can show that every extendible space-time has a (not necessarily unique) inextendible extension. What is the relationship between geodesic completeness and inextendibility? One can show that the former implies the latter (Clarke 1993). And a simple example shows that the implication does not run in the other direction.

EXAMPLE 2.—Let $(\mathbb{R}^2, \eta_{ab})$ be Minkowski space-time, and let p be any point in \mathbb{R}^2 . Let M be the manifold $\mathbb{R}^2 - \{p\}$, and let (M', g'_{ab}) be the universal covering space-time of $(M, \eta_{ab|M})$. Clearly, the space-time (M', g'_{ab}) satisfies I but not GC.

The example above shows that inextendibility is a somewhat weak condition. Indeed, some inextendible space-times that are extraordinarily well behaved (e.g., have flat metrics and manifolds diffeomorphic to \mathbb{R}^n) may nonetheless be geodesically incomplete. As before, one wonders whether there is a physically significant intermediate condition that is strong enough to rule out these seemingly artificial singularities but weak enough to allow the more physically reasonable, geodesically incomplete space-times guaranteed by the singularity theorems (see fig. 2).

One such intermediate condition was thought to have been given by Hawking and Ellis (1973). A space-time (M, g_{ab}) is said to be *locally extendible* if there is an open set $O \subset M$ with noncompact closure and an isometric embedding $\varphi : O \rightarrow M'$ into some other space-time (M', g'_{ab}) such that the closure of $\varphi(O)$ is compact. A space-time is *locally inextendible* if it is not locally extendible. Clearly, local inextendibility implies inextendibility. And the problematic example 2 given above is counted as locally extendible. But it turns out that the condition is not implied by geodesic completeness. Indeed, the condition is much too strong in the sense that Minkowski space-time can be shown to be locally extendible (Beem 1980).

5. Holes and Extensions. Hole-freeness and inextendibility are independent conditions. Example 1 shows that hole-freeness does not imply inextendibility. And example 2 shows that inextendibility does not imply hole-freeness. So, the conditions serve to rule two different types of seemingly artificial singularities. And therefore one routinely finds that both hole-

$$(GC) \implies ? \implies (I)$$

Figure 2. Is there a physically significant intermediate condition that is implied by GC and implies I?

freeness and inextendibility are assumed to be satisfied by all physically reasonable space-times (see Clarke [1976, 1993] and Earman [1989, 1995] for examples).

In the two previous sections we have wondered about the existence of two intermediate conditions: one between geodesic completeness and hole-freeness and another between geodesic completeness and inextendibility. Might there be a single (physically significant) intermediate condition that is implied by geodesic completeness and implies both hole-freeness and inextendibility (see fig. 3)? Such an intermediate condition may be strong enough to rule out, in one fell swoop, both types of seemingly artificial singularities at issue (and possibly other types as well) but weak enough to allow the more physically reasonable, geodesically incomplete space-times guaranteed by the singularity theorems.

6. An Intermediate Condition. Here, we show the existence of the intermediate condition mentioned in the previous section. We introduce the following definition.

DEFINITION 4.—A space-time (M, g_{ab}) is *effectively complete* (EC) if, for every future or past incomplete timelike geodesic $\gamma : I \rightarrow M$ and every open set O containing γ , there is no isometric embedding $\varphi : O \rightarrow M'$ into some other space-time (M', g'_{ab}) such that $\varphi \circ \gamma$ has future and past endpoints.

The condition is a variation of one found in Clarke (1982) and Earman (1989). But these authors use the mathematically cumbersome and physically dubious concept of “*b*-incomplete” curves instead of incomplete timelike geodesics.³ The physical significance of effective completeness is as follows: if a space-time fails to be effectively complete, then there is a freely falling observer who never records some particular watch reading but who “could have” in the sense that nothing in her vicinity precludes it. The condition is satisfied by the (geodesically incomplete but physically reasonable) standard “big bang” cosmological models (Wald 1984).

We note here that a variant of effective completeness can be formulated using arbitrary (instead of timelike) geodesics. The two conditions are not equivalent.⁴ But the stronger variant seems to be less significant physically

3. See Schmidt (1971) and Ellis and Schmidt (1977) for details concerning *b*-incomplete curves. See Geroch, Can-bin, and Wald (1982) and Curiel (1999) for details concerning their physical significance—or lack thereof.

4. A counterexample can be constructed by considering fig. 8.3 in Earman (1989) and “turning it on its side” so that γ is spacelike and no timelike geodesic can reach the “apex” point.

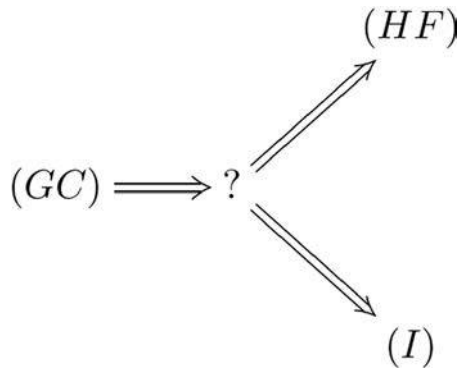


Figure 3. Is there a physically significant intermediate condition that is implied by GC and implies both HF and I?

and moreover is simply not needed to show that effective completeness implies hole-freeness and inextendibility (see below). And it follows immediately from our formulation that geodesic completeness implies effective completeness.

PROPOSITION 1.— $GC \Rightarrow EC$.

A simple example shows that the two conditions are not equivalent.

EXAMPLE 3.—Let $(\mathbb{R}^2, \eta_{ab})$ be Minkowski space-time, and let p be any point in \mathbb{R}^2 . Let M be the manifold $\mathbb{R}^2 - \{p\}$. Let $\Omega : M \rightarrow \mathbb{R}$ be a smooth, strictly positive function that approaches zero as the missing point p is approached. Let g_{ab} be the conformally flat metric $\Omega^2 \eta_{ab}$. Clearly, the space-time (M, g_{ab}) satisfies EC but not GC.

Examples 1 and 2 above show that hole-freeness and inextendibility each do not imply effective completeness. It follows as a direct corollary to proposition 1.3.1 in Clarke (1993) that a violation of inextendibility implies a violation of effective completeness. So, we have the following proposition.

PROPOSITION 2.— $EC \Rightarrow I$.

Finally, we show here that effective completeness implies hole-freeness. (All of the implication relationships between the four conditions can be summarized in fig. 4.)

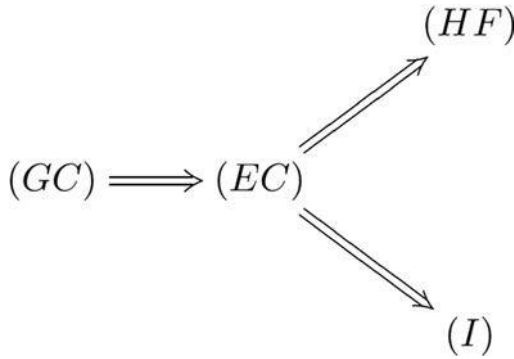


Figure 4. Relationships among EC, GC, HF, and I.

PROPOSITION 3.— $EC \Rightarrow HF$.

Proof.—Let (M, g_{ab}) be a space-time that does not satisfy HF. Then for some $K \subseteq M$ such that $(K, g_{ab|K})$ is a globally hyperbolic space-time with Cauchy surface S , we know that (i) $\text{int}(D(S)) = K$ and (ii) there is a space-time (M', g'_{ab}) and an isometric embedding $\varphi : K \rightarrow M'$ such that $\varphi[S]$ is achronal and $\varphi[K] \not\subseteq \text{int}(D(\varphi[S]))$. Without loss of generality, we may take $M' = \text{int}(D(\varphi[S]))$. So, (M', g'_{ab}) is globally hyperbolic with Cauchy surface $S' = \varphi[S]$.

Let p' be a point in K' where $K' = \varphi[K]$. Now, assume $p' \in D^+(S')$. (A similar proof can be constructed if $p' \in D^-(S')$.) Clearly, $p' \in I^+[S']$. Let $\gamma : I \rightarrow K'$ be a timelike geodesic with future endpoint p' and past endpoint in S' . Either $\varphi^{-1} \circ \gamma$ has a future endpoint or not.

First, assume $\varphi^{-1} \circ \gamma$ does not have a future endpoint. It follows that $\varphi^{-1} \circ \gamma$ is a timelike future incomplete geodesic. But by construction, $\varphi \circ \varphi^{-1} \circ \gamma = \gamma$ has future and past endpoints. So in this case, (M, g_{ab}) does not satisfy EC. Second, assume that $\varphi^{-1} \circ \gamma$ does have a future endpoint p in K . Consider the open set $U' = I^-(p') \cap I^+[S']$. Clearly, $\overline{U'} \subset K'$. Let $U = \varphi^{-1}[U']$. Note that $U \subset D^+(S)$. We also know that $\overline{U'}$ is compact (Wald 1984, theorem 8.3.12). Now, either \overline{U} is compact or not. Our next step is to show that the former case is impossible.

Assume that \overline{U} is compact. Now, let $\lambda : I \rightarrow M$ be any past inextendible casual curve with future endpoint p . Either λ leaves the set \overline{U} or not. Assume the latter case first. Since $\overline{U} \subset D^+(S)$, we can show that, for every $q \in \overline{U}$, either $q \in \dot{S}$ or every past inextendible timelike curve from q intersects S (see Wald 1984, proposition 8.3.2). But one can verify that, because λ never leaves \overline{U} , λ never intersects \dot{S} . So, for all $s \in I$, there is a timelike curve $\lambda_s : I' \rightarrow U$ with future endpoint $\lambda(s)$ and past endpoint in S . We know that, for each $s \in I$, the timelike curve $\varphi \circ \lambda_s$ has a future

endpoint in $\overline{U'}$ (Wald 1984, lemma 8.2.1). Let $\lambda' : I \rightarrow M'$ be a (continuous) causal curve defined as follows: for each $s \in I$, let $\lambda'(s)$ be the future endpoint of $\varphi \circ \lambda_s$. Since λ' is confined to $\overline{U'}$, it has a past endpoint $q' \in \overline{U'}$ (Wald 1984, lemma 8.2.1). Let $\{s_i\}$ be a sequence of points in I such that the sequence $\{\lambda'(s_i)\}$ has an accumulation point q' . Now consider the sequence $\{\lambda(s_i)\}$ in \overline{U} . Since \overline{U} is compact by assumption, $\{\lambda(s_i)\}$ has an accumulation point $q \in \overline{U}$. But this implies that λ can be extended in the past: a contradiction.

Now, assume that λ leaves \overline{U} at point $q \in \dot{U}$. For some $I' \subset I$, let $\hat{\lambda} : I' \rightarrow \overline{U}$ be the (unique) past-directed causal curve with future endpoint p and past endpoint q such that $\lambda_{|I'} = \hat{\lambda}$. There are two subcases to consider: q is in \overline{S} or not. Assume the latter. Let $\{q_i\}$ be a sequence in U that accumulates at q . The compactness of \overline{U} ensures that $\{\varphi(q_i)\}$ has an accumulation point $q' \in \overline{U'}$. Clearly, $q' \notin S'$. So, every past directed causal curve from q' must remain in $\overline{U'}$ for some interval. But this implies that every past directed causal curve from q must remain in \overline{U} for some interval: an impossibility since λ leaves \overline{U} at q .

Now assume that $q \in \overline{S}$. It is not hard to verify that q cannot be in \dot{S} . (If it were, one could find a sequence of points $\{q_i\}$ in $S \cap U$ that accumulate at q . But the sequence $\{\varphi(q_i)\}$ accumulates at a point q in S' . Therefore, $\varphi^{-1}(q') = q$ is in S : a contradiction since S is open.) Thus, λ meets S . And since λ was chosen arbitrarily, we have $p \in D^+(S)$. Now, let $\{p_i\}$ be a sequence of points in $M - \overline{D(S)}$ with limit point p . Let $\{\lambda_i\}$ be a sequence of past inextendible causal curves with corresponding future endpoints $\{p_i\}$ that also fail to meet S . We know that there is a past inextendible causal curve through p that is a limit curve of the sequence (Wald 1984, lemma 8.2.6). Since $p \in D^+(S)$, this limit curve must intersect S . But S is open, and therefore some of the $\{\lambda_i\}$ must meet S as well: a contradiction. So, \overline{U} is not compact.

Finally, let $\{r_i\}$ be a sequence of points in U without accumulation point in \overline{U} . Since $\overline{U'}$ is compact, the sequence $\{\varphi(r_i)\}$ accumulates at some point $r' \in \overline{U'}$. One can verify that r' must be in $I^+[S']$. Let $\zeta : I \rightarrow K'$ be a timelike geodesic with future endpoint r' and past endpoint in S' . Clearly, $\varphi^{-1} \circ \zeta$ has no future endpoint. It follows that $\varphi^{-1} \circ \zeta$ is a timelike future incomplete geodesic. But by construction, $\varphi \circ \varphi^{-1} \circ \zeta = \zeta$ has future and past endpoints. So in this case as well, (M, g_{ab}) does not satisfy EC. QED

7. Conclusion. One final note on how the causal structure of space-time is connected with the preceding.⁵ Of course, under the assumption of any

5. For a recent related discussion on causal structure and an alternate version of hole-freeness, see Minguzzi (2012).

$$(GC) \implies (EC) \implies (I) \implies (HF)$$

Figure 5. Relationships among GC, EC, I, and HF under the assumption of global hyperbolicity.

causal condition, the implication relations outlined in the previous section remain intact. And all the counterexamples given satisfy stable causality (and therefore any causal condition it implies). What about the stronger causal condition of global hyperbolicity?

One can easily find globally hyperbolic examples showing that effective completeness does not imply geodesic incompleteness, inextendibility does not imply effective completeness, hole-freeness does not imply effective completeness, and hole-freeness does not imply inextendibility. (All of the examples can be constructed using the manifold in example 1 and adding various conformally flat metrics.)

But it turns out that under the assumption of global hyperbolicity, we find that inextendibility implies hole-freeness (Manchak 2009). It has been conjectured (Penrose 1979) that all physically reasonable space-times are globally hyperbolic. Thus, if the conjecture is true, we seem to have a useful hierarchy of conditions (see fig. 5).

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