

Malament-Hogarth Machines*

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Abstract

We show a clear sense in which general relativity allows for a type of “machine” which can bring about a spacetime structure suitable for the implementation of “supertasks.”

1 Introduction

In what follows, the intersection of two concepts in the foundations of general relativity is investigated: (1) Malament-Hogarth spacetimes which allow for a type of “supertask” in which a future infinite timelike curve is contained in the past of a spacetime event and (2) “machine” spacetimes which bring about various properties from initial conditions (e.g. “time machines” are spacetimes which bring about a particular type of unusual causal structure). After introducing a quite general characterization of machine spacetimes, we consider various definitions of “Malament-Hogarth machines” and show their existence. The upshot of our work is this: there a clear sense in which general relativity allows for a type of machine which can bring about a spacetime structure suitable for the implementation of supertasks. We close by outlining a program for future work on the subject.

2 Preliminaries

We begin with a few preliminaries concerning the relevant background formalism of general relativity.¹ An n -dimensional, relativistic *spacetime* (for $n \geq 2$) is a

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¹The reader is encouraged to consult Hawking and Ellis (1973), Wald (1984), and Malament (2012) for details. An outstanding (and less technical) survey of the global structure of spacetime is given by Geroch and Horowitz (1979).

pair of mathematical objects (M, g_{ab}) : M is a smooth (connected) n -dimensional manifold and g_{ab} is a smooth metric on M of Lorentz signature $(+, -, \dots, -)$. Note that M is assumed to be *Hausdorff*; for any distinct $p, q \in M$, one can find disjoint open sets O_p and O_q containing p and q respectively.

For each point $p \in M$, the metric assigns a cone structure to the tangent space M_p . Any tangent vector ξ^a in M_p will be *timelike* if $g_{ab}\xi^a\xi^b > 0$, *null* if $g_{ab}\xi^a\xi^b = 0$, or *spacelike* if $g_{ab}\xi^a\xi^b < 0$. Null vectors create the cone structure; timelike vectors are inside the cone while spacelike vectors are outside. A *time orientable* spacetime is one that has a continuous timelike vector field on M . A time orientable spacetime allows one to distinguish (globally and continuously) between the future and past lobes of the light cone. In what follows, it is assumed that spacetimes are time orientable and that an orientation has been chosen.

For some connected interval $I \subseteq \mathbb{R}$, a smooth curve $\gamma : I \rightarrow M$ is *timelike* if the tangent vector ξ^a at each point in $\gamma[I]$ is timelike. Similarly, a curve is *null* (respectively, *spacelike*) if its tangent vector at each point is null (respectively, spacelike). A curve is *causal* if its tangent vector at each point is either null or timelike. A causal curve is *future-directed* if its tangent vector at each point falls in or on the future lobe of the light cone. For any smooth curve $\gamma : I \rightarrow M$ with tangent field ξ^a , the *length* $\|\gamma\|$ is given by $\int_\gamma (\xi^a\xi_a)^{\frac{1}{2}} ds$. When γ is timelike, its length represents the elapsed proper time along the curve.

A point $p \in M$ is a *future endpoint* of a future-directed causal curve $\gamma : I \rightarrow M$ if, for every neighborhood O of p , there exists a point $t_0 \in I$ such that $\gamma(t) \in O$ for all $t > t_0$. A *past endpoint* is defined similarly. A causal curve is *future inextendible* (respectively, *past inextendible*) if it has no future (respectively, past) endpoint. We say a curve $\gamma : I \rightarrow M$ is not *maximal* if there is another curve $\gamma' : I' \rightarrow M$ such that I is a proper subset of I' and $\gamma(s) = \gamma'(s)$ for all $s \in I$. A curve $\gamma : I \rightarrow M$ in a spacetime (M, g_{ab}) is a *geodesic* if $\xi^a\nabla_a\xi^b = \mathbf{0}$ where ξ^a is the tangent vector and ∇_a is the unique derivative operator such that $\nabla_a g_{bc}$. A spacetime (M, g_{ab}) is *geodesically complete* if every maximal geodesic $\gamma : I \rightarrow M$ is such that $I = \mathbb{R}$. If an incomplete geodesic is timelike or null, there is a useful distinction one can introduce: We say that a future-directed timelike or null geodesic $\gamma : I \rightarrow M$ without future endpoint is *future incomplete* if there is an $r \in \mathbb{R}$ such that $s < r$ for all $s \in I$. A *past incomplete* timelike or null geodesic is defined analogously. A spacetime (M, g_{ab}) is *effectively complete* if, for every future or past incomplete timelike geodesic $\gamma : I \rightarrow M$, and every open set O containing γ , there is no isometric embedding $\varphi : O \rightarrow M'$ into some other spacetime (M', g'_{ab}) such that $\varphi \circ \gamma$ has future and past endpoints.

For any two points $p, q \in M$, we write $p \ll q$ if there exists a future-directed timelike curve from p to q . We write $p < q$ if there exists a future-directed causal curve from p to q . These relations allow us to define the *timelike and causal pasts and futures* of a point p : $I^-(p) = \{q : q \ll p\}$, $I^+(p) = \{q : p \ll q\}$, $J^-(p) = \{q : q < p\}$, and $J^+(p) = \{q : p < q\}$. A spacetime satisfies *chronology* if there is no $p \in M$ such that $p \in I^+(p)$. A spacetime which violates chronology has timelike curves $\gamma : [s_0, s_1] \rightarrow M$ such that $\gamma(s_0) = \gamma(s_1)$; such timelike

curves are called *closed*. We say a spacetime satisfies *strong causality* if, for all points $p \in M$ and every open set O containing p , there is an open set $V \subset O$ also containing p such that no causal curve intersects V more than once. A spacetime satisfies *stable causality* if there is a smooth function $t : M \rightarrow \mathbb{R}$ such that for any distinct points $p, q \in M$, if $q \in J^+(p)$, then $t(p) < t(q)$.

A set $S \subset M$ is *achronal* if no two points in S can be connected by a timelike curve. The *edge* of a closed, achronal set $S \subset M$ is the set of points $p \in S$ such that every open neighborhood O of p contains a point $q \in I^+(p)$, a point $r \in I^-(p)$, and a timelike curve from r to q which does not intersect S . A set $S \subset M$ is a *slice* if it is closed, achronal, and without edge. For any set $S \subset M$, we define the *domain of dependence of S* , written $D(S)$, to be the set of points $p \in M$ such that every inextendible causal curve through p intersects S . A spacetime (M, g_{ab}) which contains a slice S such that $D(S) = M$ is said to be *globally hyperbolic*. In such a spacetime, we say S is a *Cauchy surface*.

Two spacetimes (M, g_{ab}) and (M', g'_{ab}) are *isometric* if there is a diffeomorphism $\psi : M \rightarrow M'$ such that $\psi_*(g_{ab}) = g'_{ab}$. We say a spacetime (M', g'_{ab}) is an *extension* of (M, g_{ab}) if there is a proper subset N of M' such that (M, g_{ab}) and (N, g'_{ab}) are isometric. We say a spacetime is *maximal* if it has no extension. A spacetime (M, g_{ab}) is *past-maximal* if, for each of its maximal extensions (M', g'_{ab}) with isometric embedding $\psi : M \rightarrow M'$, we have $I^-(\psi(M)) = \psi(M)$. A *future-maximal* spacetime is defined analogously.

3 Malament-Hogarth Spacetimes

Roughly, a supertask is “a task that consists in infinitely many component steps, but which in some sense is completed in a finite amount of time” (Manchak and Roberts 2016). It has been argued that some models of general relativity – those models called “Malament-Hogarth” spacetimes – have a causal structure suitable for the implementation of supertasks of a certain kind.² The idea is beautifully simple. Consider the following definition.

Definition. A spacetime (M, g_{ab}) is *Malament-Hogarth* if there is a past-extendible timelike curve $\gamma : I \rightarrow M$ and a point $p \in M$ such that (i) $\|\gamma\| = \infty$ and (ii) $\gamma[I] \subset I^-(p)$.

Consider a Malament-Hogarth spacetime (M, g_{ab}) and let $p \in M$ and $\gamma : I \rightarrow M$ be as in the definition. Let q be the past endpoint of γ . The points q and p represent, respectively, the beginning and the end of the supertask. At q , consider two observers (call them A and B) who decide to take very different future paths through spacetime. Observer A follows the path along γ . Observer B takes any path from q to p . (It follows from condition (ii) that a timelike curve exists with past endpoint q and future endpoint p .) Condition (ii) ensures

²See, for example, the following: Pitowski 1990; Hogarth 1992, 1994; Earman and Norton 1993, 1996; Etesi, G., and I. Németi 2002; Manchak 2010; Manchak and Roberts 2016; Andr eka et al. 2017.

that a signal can be sent from any point along γ to the point p . Condition (i) ensures that observer A has an infinite amount of future time along γ . Thus, there is a sense in which observer B can, from the point p , “view an eternity in a finite time” (Hogarth 1992).

Anti-de Sitter spacetime is the paradigm Malament-Hogarth example (see Earman and Norton 1993). In two dimensions, the spacetime is (M, g_{ab}) where $M = \mathbb{R}^2$ and $g_{ab} = \cosh^2 x \nabla_a t \nabla_b t - \nabla_a x \nabla_b x$. By inspection we see that the light cones widen rapidly as $|x| \rightarrow \infty$. It turns out that because of this fact, there exist past-extendible timelike curves $\gamma : I \rightarrow M^-$ such that $\|\gamma\| = \infty$ where $M^- = \{(t, x) \in M : t < 0\}$. Moreover, there are points p such that $M^- \subset I^-(p)$. It follows that anti-de Sitter spacetime is Malament-Hogarth. Anti-de Sitter spacetime fails to be globally hyperbolic and this turns out to be a general feature shared by all Malament-Hogarth spacetimes. We have the following (Hogarth 1992).

Proposition. All Malament-Hogarth spacetimes fail to be globally hyperbolic.

The cosmic censorship hypothesis as championed by Penrose (1979, 1999) can be stated as: “All physically reasonable spacetimes are globally hyperbolic” (Wald 1984, 304). If this hypothesis were true, then it would follow that no Malament-Hogarth spacetime is physically reasonable. Those interested in Malament-Hogarth spacetimes can breathe a sigh of relief though: the status of Penrose’s version of the cosmic censorship hypothesis is far from settled (see Earman 1995). And recent work underscores just how difficult it would be to establish that all Malament-Hogarth spacetimes are physically unreasonable (Manchak and Roberts 2016, Andr eka et al. 2017).

4 Machines

Malament-Hogarth spacetimes are certainly fascinating. But we are ultimately interested in the possibility of “bringing about” their properties in our own universe. We know that whatever else is the case, one cannot make sense of this “bringing about” by employing the usual notion of causal determinism present in general relativity; as mentioned above, a globally hyperbolic spacetime can never be Malament-Hogarth. The literature on “machines” – especially “time machines” and “hole machines” (Earman, W uthrich, and Manchak 2016) – provides a framework to understand the “bringing about” notion in a quite general way.³ Consider the following.

Definition. A past-maximal, globally hyperbolic spacetime is a $(\mathcal{P}, \mathcal{Q})$ -*machine* if (i) some extension to the spacetime has property \mathcal{P} and (ii) every extension which has property \mathcal{P} also has property \mathcal{Q} .

³See also: Earman 1995; Earman, Smeenk, and W uthrich 2009; Geroch 1982; Krasnikov 2002, 2014; Manchak 2009b, 2009c, 2011a, 2013, 2014a; Smeenk and W uthrich 2010.

A past-maximal, globally hyperbolic spacetime represents a “time” before the machine is switched on; let us call such a spacetime a *starter* in what follows. Property \mathcal{P} is used to pare down the space of starter extensions to those which are “physically reasonable” in some sense.⁴ For example, \mathcal{P} might be a property which guarantees a “nice” causal structure (see below for concrete examples of candidate properties \mathcal{P}). Property \mathcal{Q} is the one intended to be brought about by the machine. Condition (ii) captures the idea that all “physically reasonable” starter extensions have \mathcal{Q} . Condition (i) is added to avoid a nuisance case; we don’t want to count a starter as a $(\mathcal{P}, \mathcal{Q})$ -machine simply because (ii) is vacuously true.

Research on $(\mathcal{P}, \mathcal{Q})$ -machines has (so far) focused primarily on existence results where \mathcal{Q} is the failure of chronology. Consider the following “time machine” existence result, for example (Manchak 2011a). Here, a spacetime (M, g_{ab}) is *J-closed* if, for all $p \in M$, the sets $J^-(p)$ and $J^+(p)$ are topologically closed.

Proposition. There exist $(\mathcal{P}, \mathcal{Q})$ -machines where \mathcal{P} is J-closedness and \mathcal{Q} is the failure of chronology.

The starter used to exhibit the above proposition is the “bottom half” of Misner spacetime (see Hawking and Ellis 1973). Consider Misner spacetime (M, g_{ab}) : $M = \mathbb{R} \times S$ and $g_{ab} = 2\nabla_{(a}t\nabla_{b)}\varphi + t\nabla_a\varphi\nabla_b\varphi$ where the points (t, φ) are identified with the points $(t, \varphi + 2\pi n)$ for all integers n . The bottom half of Misner spacetime is (M^-, g_{ab}) where $M^- = \{(t, \varphi) \in M : t < 0\}$. One can verify that (M^-, g_{ab}) is a starter; it is past-maximal and globally hyperbolic. Now, some extensions to the starter are J-closed and some are not. But it turns out that all extensions to the starter which are J-closed fail to be chronological.

We close this section with a word concerning the structure of existence results like those considered above. Suppose for some properties \mathcal{P} and \mathcal{Q} one finds there is a $(\mathcal{P}, \mathcal{Q})$ -machine. It is important to note that one’s choice of \mathcal{P} is, in general, crucial for the existence result to go through: If $\mathcal{P}_0 \Rightarrow \mathcal{P} \Rightarrow \mathcal{P}_1$ for some properties $\mathcal{P}_0, \mathcal{P}_1$, there is no guarantee that either a $(\mathcal{P}_0, \mathcal{Q})$ -machine or a $(\mathcal{P}_1, \mathcal{Q})$ -machine exists. The former is not guaranteed since \mathcal{P}_0 may be so strong that the starter used to exhibit the $(\mathcal{P}, \mathcal{Q})$ -machine may not even have a \mathcal{P}_0 extension. The latter is not guaranteed either; if the class of “physically reasonable” spacetimes is enlarged by \mathcal{P}_1 , it is possible that the starter used to exhibit the $(\mathcal{P}, \mathcal{Q})$ -machine may be such that one of its \mathcal{P}_1 -but-not- \mathcal{P} extensions is not \mathcal{Q} .

5 Malament-Hogarth Machines

Using the framework from the preceding section, one defines a “Malament-Hogarth machine” to be a $(\mathcal{P}, \mathcal{Q})$ -machine where \mathcal{Q} is the property of being

⁴See Manchak 2009a, 2011b for a discussion of our epistemic limitations in determining the class of “physically reasonable” spacetimes.

a Malament-Hogarth spacetime. What about \mathcal{P} ? As noted above, one's choice of \mathcal{P} is generally quite important; an existence result may fail if \mathcal{P} is either too strong or too weak.

One often restricts attention to “physically reasonable” spacetimes by invoking a pair of global conditions – one to rule out artificial “holes” in spacetime and one to rule out “bad” causal structure (see Earman 1995). There are two useful logical hierarchies to consider. We have a “no-holes” hierarchy (Manchak 2014b): geodesic completeness (GC) \Rightarrow effective completeness (EC) \Rightarrow maximality (M). And we have a (simplified) hierarchy of causal conditions (Wald 1984): global hyperbolicity (GH) \Rightarrow stable causality (SC) \Rightarrow strong causality (Str) \Rightarrow chronology (C). Using these hierarchies, one can settle a quite a few questions concerning Malament-Hogarth machines in one fell swoop. We have the following.

Proposition. There exist $(\mathcal{P}, \mathcal{Q})$ -machines where \mathcal{Q} is the property of being Malament-Hogarth and \mathcal{P} is any property such that $((\text{SC}) \ \& \ (\text{GC})) \Rightarrow \mathcal{P}$.

Proof. Here we construct an example which is conformally equivalent to a portion of Minkowski spacetime. The example is two-dimensional for the sake of simplicity but can be easily generalized to any dimension $n \geq 2$.

Consider Minkowski spacetime $(\mathbb{R}^2, \eta_{ab})$ in standard (t, x) coordinates: $\eta_{ab} = \nabla_a t \nabla_b t - \nabla_a x \nabla_b x$. Let us agree that our temporal orientation is such that the vector $(\partial/\partial t)^a$ is future-directed. Let $M = \mathbb{R}^2 - J^+((0, 0))$ and let $g_{ab} = \Omega^2 \eta_{ab}$ where the function $\Omega : M \rightarrow \mathbb{R}$ is defined by $\Omega(t, x) = (t^2 + x^2)^{-1}$. The spacetime (M, g_{ab}) is conformally equivalent to (and therefore has the same causal structure as) the portion (M, η_{ab}) of Minkowski spacetime. Since (M, η_{ab}) is globally hyperbolic, so is (M, g_{ab}) . (The set $\{(t, x) \in M : t = -1\}$ is one Cauchy surface.) By construction, (M, g_{ab}) is past-maximal. We now show that any extension to (M, g_{ab}) is a Malament-Hogarth spacetime.

Let (M', g'_{ab}) be any extension at all of (M, g_{ab}) . Consider the curve $\gamma : (0, 1) \rightarrow M$ defined by $\gamma(s) = (s - 1, 0)$. So the tangent vector ξ^a is $(\partial/\partial t)^a$ at every point along γ . Thus, γ is a future-directed timelike curve with past endpoint $(-1, 0)$. We have $dt/ds = \xi^a \nabla_a t = 1$ and so $\|\gamma\| = \int_\gamma (\xi^a \xi_a)^{\frac{1}{2}} ds = \int_\gamma (\xi^a \xi_a)^{\frac{1}{2}} dt$. Because $\xi^a \xi_a = \Omega^2$ we have $\int_\gamma (\xi^a \xi_a)^{\frac{1}{2}} dt = \int_\gamma (t^2 + x^2)^{-1} dt$. But since $x = 0$ along γ , the last quantity simplifies to $\int_\gamma t^{-2} dt = -t^{-1} \Big|_{-1}^0 = \infty$.

Let $p \in M'$ be any point on the boundary of M . One can extend the coordinate system on M to $M \cup O$ for some neighborhood O of p . Clearly, $p = (p_t, p_x)$ is such that $p_t > 0$ and $|p_x| = p_t$. Without loss of generality, let us assume that $p_t = p_x$. (An analogous argument can be given for $p_t = -p_x$.) Let $q = (q_t, 0)$ be any point on $\gamma[I]$. Let $\lambda : [0, 1] \rightarrow M'$ be defined by $\lambda(s) = ((p_t - q_t)s + q_t, sp_x)$. We find that the tangent vector ζ^a at every point along λ is $(p_t - q_t)(\partial/\partial t)^a + p_x(\partial/\partial x)^a$. So $\zeta^a \zeta_a = \Omega^2[(p_t - q_t)^2 - p_x^2]$. Because $p_t = p_x > 0$ and $q_t < 0$, we see that ζ^a is a future-directed timelike vector. Since $\lambda(0) = q$ and $\lambda(1) = p$, it follows that $p \in I^+(q)$. Since q is an arbitrary point on $\gamma[I]$, we have $\gamma[I] \subset I^-(p)$. Thus, (M', g'_{ab}) is a Malament-Hogarth spacetime.

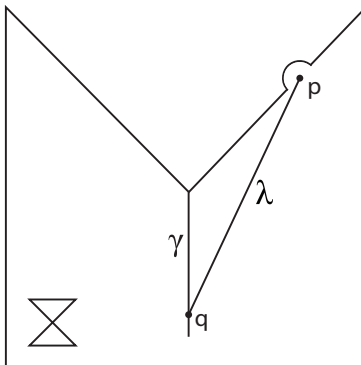


Figure 1: The region $M \cup O$ of M' . A future-directed timelike curve λ can be constructed from every point $q \in \gamma[I]$ to the point p .

We are done if we can find an extension to (M, g_{ab}) which is stably causal and geodesically complete. But this is easy: consider the extension (M', g'_{ab}) such that $M' = \mathbb{R}^2 - \{(0, 0)\}$ and $g'_{ab} = \Omega'^2 \eta_{ab}$ where the function $\Omega' : M' \rightarrow \mathbb{R}$ is defined by $\Omega'(t, x) = (t^2 + x^2)^{-1}$. \square

6 Conclusion

We have shown above that there exist $(\mathcal{P}, \mathcal{Q})$ -machines where \mathcal{Q} is the property of being Malament-Hogarth and \mathcal{P} is any property such that $((\text{SC}) \ \& \ (\text{GC})) \Rightarrow \mathcal{P}$. The result is robust in the sense that it is not sensitive to the choice of property \mathcal{P} so long as \mathcal{P} is the conjunction of any one of the “no-holes” conditions and any one of the weak to moderate causal conditions. Moreover, \mathcal{P} could even be a “universal property” (i.e. some property satisfied by all spacetimes) and the proposition would go through. In other words, unlike the situation for “time machines” (see Earman, Wüthrich, and Manchak 2016), one need not pare down the class of “physically reasonable” spacetimes to obtain a Malament-Hogarth machine existence result.

We close with a suggestion for future work. In the preceding, no imposition has been made on the local structure of spacetime; in particular, Einstein’s equation (with some reasonable matter source) did not enter into the discussion. Essentially, we have leaned heavily on the idea that “one’s lack of concern with Einstein’s equation in these examples is a reflection of the experience that things which can happen in the absence of this equation can usually also happen in its presence” (Geroch and Horowitz 1979, 215). That said, it might be of interest to see if an existence result can still be obtained if one restricts attention to Malament-Hogarth spacetimes whose stress energy tensor T_{ab} (given by Einstein’s equation) satisfies some energy condition or other.

Let (E) be any one of several energy condition of interest (see Curiel 2017).

Given the hierarchies mentioned in the previous section, sixteen open questions present themselves which, without further argument, are independent of each other. (There is plenty of work to do here!)

Question. Do there exist $(\mathcal{P}, \mathcal{Q})$ -machines if \mathcal{Q} is the property of being Malament-Hogarth and \mathcal{P} is any one of the following?

1. (E)
2. (E) & (M)
3. (E) & (EC)
4. (E) & (GC)
5. (E) & (C)
6. (E) & (C) & (M)
7. (E) & (C) & (EC)
8. (E) & (C) & (GC)
9. (E) & (Str)
10. (E) & (Str) & (M)
11. (E) & (Str) & (EC)
12. (E) & (Str) & (GC)
13. (E) & (SC)
14. (E) & (SC) & (M)
15. (E) & (SC) & (EC)
16. (E) & (SC) & (GC)

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